

Preconditioning of the Two Fluid Equations to Avoid Excessive Dissipation

L'CADAME Weekly Meetings

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Laboratório de Computação de Alto Desempenho e
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Weekly Meetings

Governing Equations

$$\begin{aligned}\frac{\partial \rho}{\partial t} + \frac{\partial \rho u}{\partial x} &= 0 \\ \frac{\partial \rho u}{\partial t} + \frac{\partial \rho u^2 + p}{\partial x} &= 0\end{aligned}\quad (1)$$

Nondimensionalization

Lets scale everything using

$$\begin{aligned}\bar{\rho} &= \frac{\rho}{\rho^*} \quad ; \quad \bar{u} = \frac{u}{u^*} \\ \bar{p} &= \frac{p}{\rho^* a^{*2}} \quad ; \quad \bar{x} = \frac{x}{\delta^*} \\ & \quad \quad \quad \bar{t} = \frac{t \delta^*}{u^*}\end{aligned}\quad (2)$$

Nondimensionalization

$$\begin{aligned} \frac{\partial \rho}{\partial t} + \frac{\partial \rho u}{\partial x} &= 0 \\ \frac{\partial \rho u}{\partial t} + \frac{\partial \rho u^2}{\partial x} + \frac{1}{M_*^2} \frac{\partial p}{\partial x} &= 0 \end{aligned} \quad (3)$$

Limit of low Mach number

$$\begin{aligned} \rho &= \rho_0 + \rho_1 M_* + \rho_2 M_*^2 + \dots \\ u &= u_0 + u_1 M_* + u_2 M_*^2 + \dots \\ p &= p_0 + p_1 M_* + p_2 M_*^2 + \dots \end{aligned} \quad (4)$$

M_*^{-2} Terms

$$\frac{\partial p_0}{\partial x} = 0 \quad (5)$$

M_*^{-1} Terms

$$\frac{\partial p_1}{\partial x} = 0 \quad (6)$$

M_*^0 Terms

$$\frac{\partial \rho_0 u_0}{\partial t} + \frac{\partial \rho_0 u_0^2}{\partial x} + \frac{\partial p_2}{\partial x} = 0 \quad (7)$$

Forcing constant pressure on the boundary will result

$$p(x, t) = p_0(t) + p_2(x, t)M_*^2 + \dots \quad (8)$$

Governing Equations

$$\begin{aligned} \frac{\partial \rho}{\partial t} + \frac{\partial \rho u}{\partial x} &= 0 \\ \frac{\partial \rho u}{\partial t} + \frac{\partial \rho u^2 + p}{\partial x} &= 0 \end{aligned} \quad (9)$$

$$\frac{\partial q}{\partial t} + A \frac{\partial q}{\partial x} = 0 \quad (10)$$

$$q = [\rho, \rho u]^T \quad (11)$$

$$A = \begin{bmatrix} 0 & 1 \\ c^2 - u^2 & 2u \end{bmatrix} \quad (12)$$

$$\lambda_{1,2} = u \pm c \quad ; \quad R = \begin{bmatrix} 1 & 1 \\ u - c & u + c \end{bmatrix} \quad (13)$$

Godunov Method

$$\frac{\partial Q_i}{\partial t} + \frac{1}{\Delta x} (A^+ \Delta Q_{i-1/2} + A^- \Delta Q_{i+1/2}) = 0 \quad (14)$$

$$A^+ \Delta Q_{i-1/2} = \sum_{p=0}^2 (\lambda_{i-1/2}^p)^+ W_{i-1/2}^p \quad (15)$$

$$A^- \Delta Q_{i+1/2} = \sum_{p=0}^2 (\lambda_{i+1/2}^p)^- W_{i+1/2}^p$$

$$\lambda^\pm = \frac{1}{2}(\lambda + |\lambda|) \quad ; \quad W_{i-1/2}^p = \beta_{i-1/2}^p r_{i-1/2}^p \quad (16)$$

$$\beta_{i-1/2}^p = R_{i-1/2}^{-1} (Q_i - Q_{i-1}) \quad (17)$$

Godunov Method

$$\begin{aligned} \frac{\partial Q_i}{\partial t} + \frac{1}{\Delta x} (A^+ \Delta Q_{i-1/2} + A^- \Delta Q_{i+1/2}) &= 0 \\ A^+ \Delta Q_{i-1/2} &= \frac{1}{4} \rho^* u^* M \left(\hat{u}_1 + M^{*-1} \right) \times \\ &[(M^{*-1} - \hat{u}_1) \Delta \rho_1 + \Delta(\rho u)_1] \begin{bmatrix} 1 \\ u^* \hat{u}_1 + c \end{bmatrix} \\ A^- \Delta Q_{i+1/2} &= \frac{1}{4} \rho^* u^* M^* \left(\hat{u}_2 - M^{*-1} \right) \times \\ &[(M^{*-1} + \hat{u}_2) \Delta \rho_2 - \Delta(\rho u)_2] \begin{bmatrix} 1 \\ u^* \hat{u}_2 - c \end{bmatrix} \end{aligned} \quad (18)$$

$$\begin{aligned} \frac{\partial \rho}{\partial t} + \frac{\hat{\delta}}{4} M^* (\hat{u}_2 - M^{*-1}) [(M^{*-1} + \hat{u}_2) \Delta \rho_2 - \Delta(\rho u)_2] \\ + \frac{\hat{\delta}}{4} M (\hat{u}_1 + M^{*-1}) [(M^{*-1} - \hat{u}_1) \Delta \rho_1 + \Delta(\rho u)_1] = 0 \end{aligned} \quad (19)$$

$$\begin{aligned} \frac{\partial \rho u}{\partial t} + \frac{\hat{\delta}}{4} M^* (\hat{u}_2 - M^{*-1})^2 [(M^{*-1} + \hat{u}_2) \Delta \rho_2 - \Delta(\rho u)_2] \\ + \frac{\hat{\delta}}{4} M (\hat{u}_1 + M^{*-1})^2 [(M^{*-1} - \hat{u}_1) \Delta \rho_1 + \Delta(\rho u)_1] = 0 \end{aligned} \quad (20)$$

Continuity M_*^{-1}

$$-(\rho_{i+1}^0 - \rho_i^0) + (\rho_i^0 - \rho_{i-1}^0) = 0 \quad (21)$$

$$\begin{aligned} \frac{\partial \rho}{\partial t} + \frac{\hat{\delta}}{4} M^* (\hat{u}_2 - M^{*-1}) [(M^{*-1} + \hat{u}_2) \Delta \rho_2 - \Delta(\rho u)_2] \\ + \frac{\hat{\delta}}{4} M (\hat{u}_1 + M^{*-1}) [(M^{*-1} - \hat{u}_1) \Delta \rho_1 + \Delta(\rho u)_1] = 0 \end{aligned} \quad (22)$$

$$\begin{aligned} \frac{\partial \rho u}{\partial t} + \frac{\hat{\delta}}{4} M^* (\hat{u}_2 - M^{*-1})^2 [(M^{*-1} + \hat{u}_2) \Delta \rho_2 - \Delta(\rho u)_2] \\ + \frac{\hat{\delta}}{4} M (\hat{u}_1 + M^{*-1})^2 [(M^{*-1} - \hat{u}_1) \Delta \rho_1 + \Delta(\rho u)_1] = 0 \end{aligned} \quad (23)$$

Momentum M_*^{-2}

$$(\rho_{i+1}^0 - \rho_i^0) + (\rho_i^0 - \rho_{i+1}^0) = 0 \quad (24)$$

$$\begin{aligned} -(\rho_{i+1}^0 - \rho_i^0) + (\rho_i^0 - \rho_{i-1}^0) &= 0 \\ (\rho_{i+1}^0 - \rho_i^0) + (\rho_i^0 - \rho_{i+1}^0) &= 0 \end{aligned} \quad (25)$$

Results in

$$\rho_i^0 = \rho_{i+1}^0 = \rho_{i-1}^0 \quad (26)$$

$$\begin{aligned} \frac{\partial \rho}{\partial t} + \frac{\hat{\delta}}{4} M^* (\hat{u}_2 - M^{*-1}) [(M^{*-1} + \hat{u}_2) \Delta \rho_2 - \Delta(\rho u)_2] \\ + \frac{\hat{\delta}}{4} M (\hat{u}_1 + M^{*-1}) [(M^{*-1} - \hat{u}_1) \Delta \rho_1 + \Delta(\rho u)_1] = 0 \end{aligned} \quad (27)$$

$$\begin{aligned} \frac{\partial \rho u}{\partial t} + \frac{\hat{\delta}}{4} M^* (\hat{u}_2 - M^{*-1})^2 [(M^{*-1} + \hat{u}_2) \Delta \rho_2 - \Delta(\rho u)_2] \\ + \frac{\hat{\delta}}{4} M (\hat{u}_1 + M^{*-1})^2 [(M^{*-1} - \hat{u}_1) \Delta \rho_1 + \Delta(\rho u)_1] = 0 \end{aligned} \quad (28)$$

Momentum M_*^{-1}

$$\rho_{i+1}^1 - \rho_{i-1}^1 = \rho^0 (-u_{i+1}^0 + 2u_i^0 - u_{i-1}^0) \quad (29)$$

$$\begin{aligned} -(\rho_{i+1}^0 - \rho_i^0) + (\rho_i^0 - \rho_{i-1}^0) &= 0 \\ (\rho_{i+1}^0 - \rho_i^0) + (\rho_i^0 - \rho_{i+1}^0) &= 0 \\ \rho_{i+1}^1 - \rho_{i-1}^1 &= \rho^0(-u_{i+1}^0 + 2u_i^0 - u_{i-1}^0) \end{aligned} \quad (30)$$

ρ^1 is not zero!

$$p = p_0 + c^2(\rho - \rho_0) \quad (31)$$

This means P^1 is not also zero!